

FIG. 1

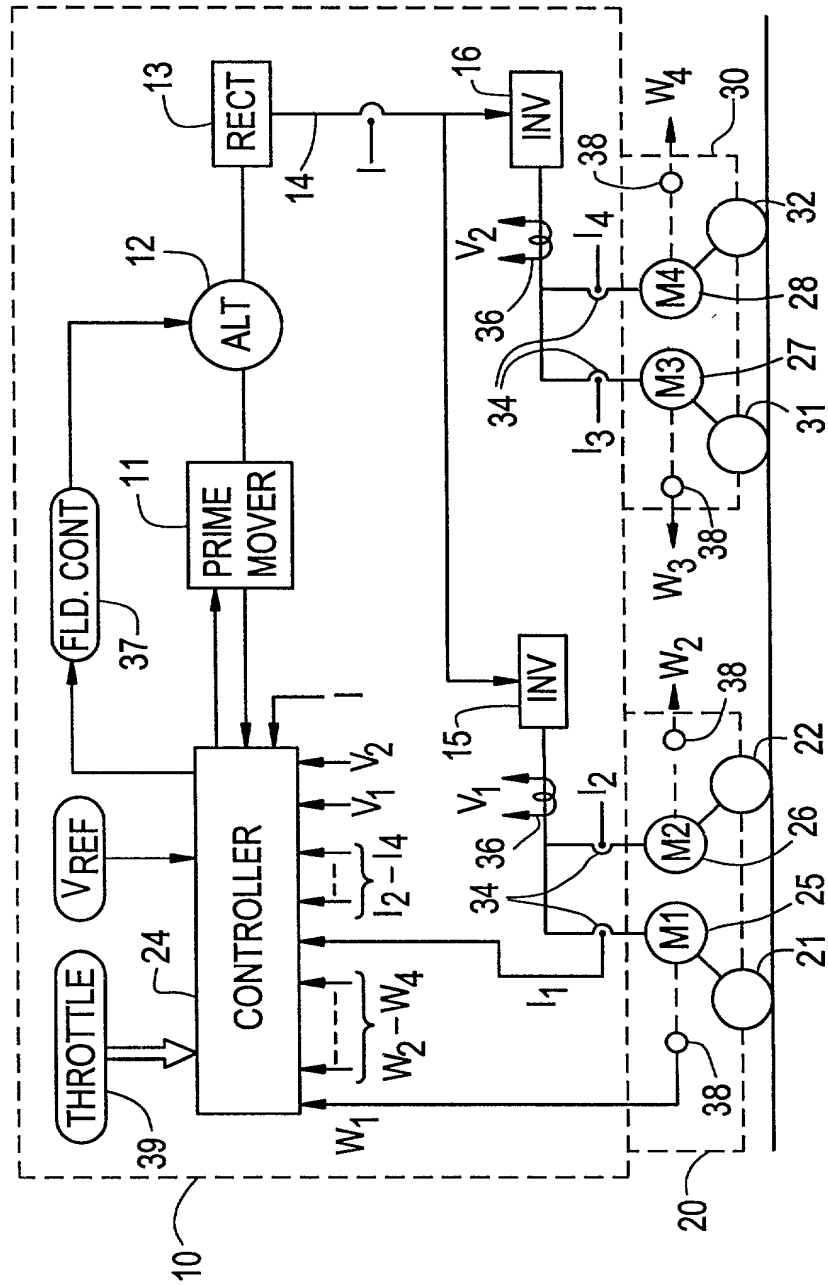


FIG. 2A

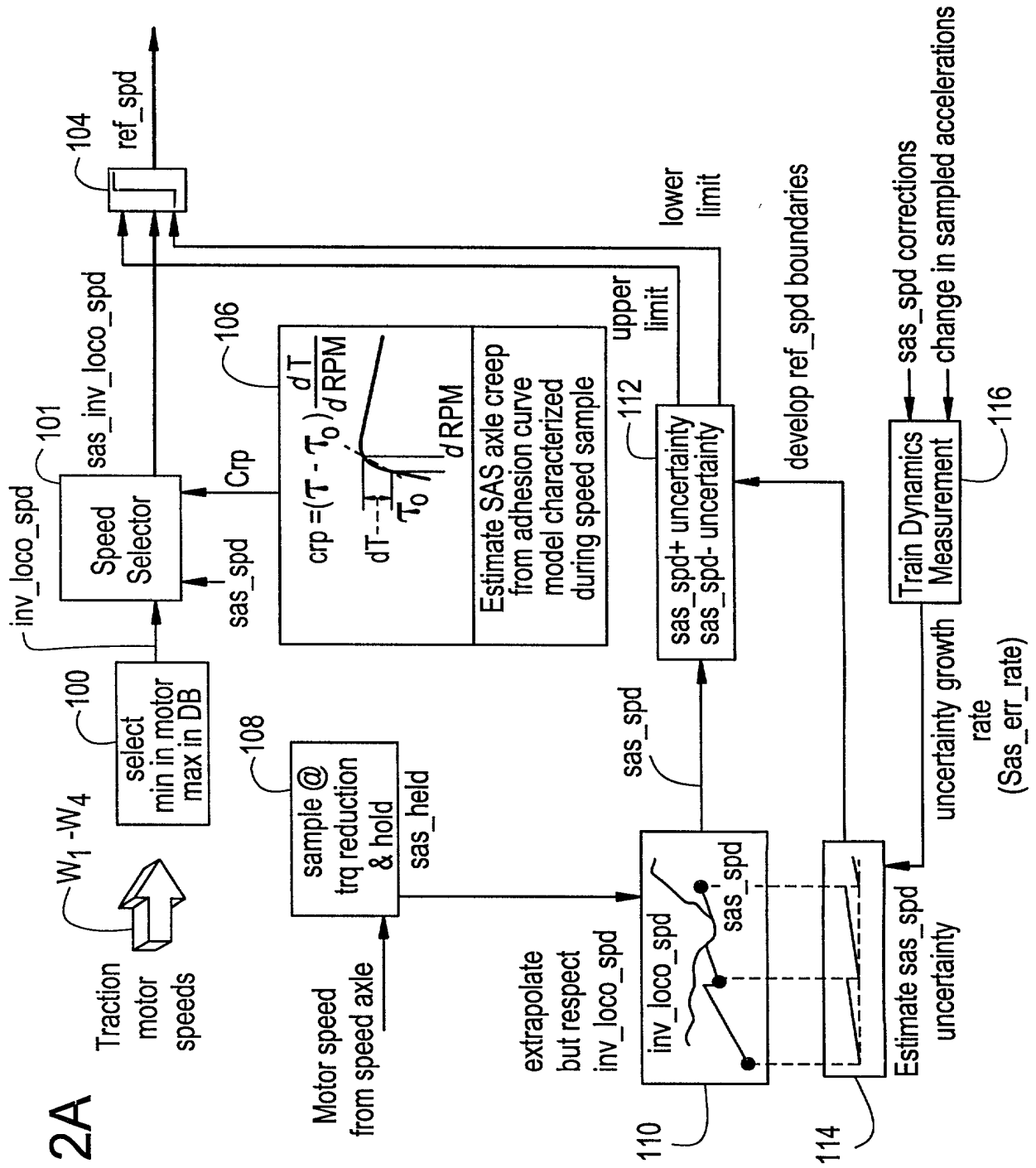
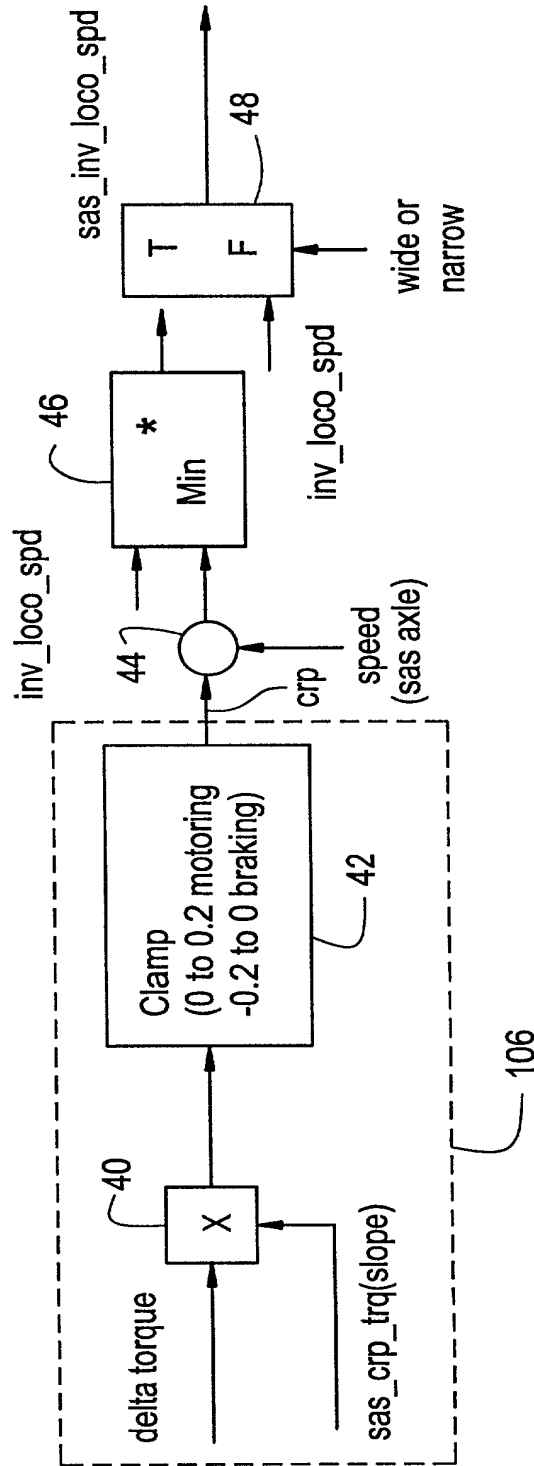


FIG. 2B



\* Min if motoring &  
Max if Braking

FIG. 2C

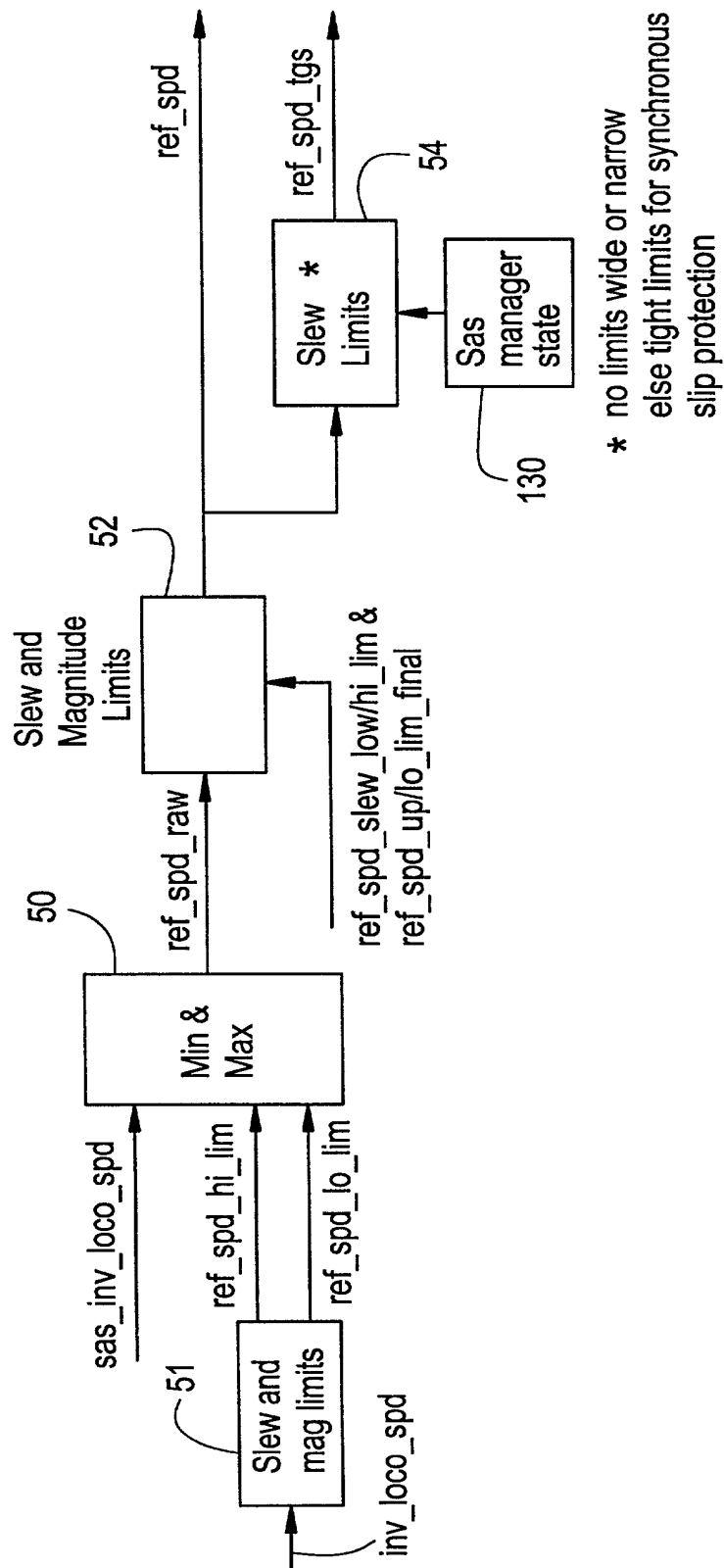
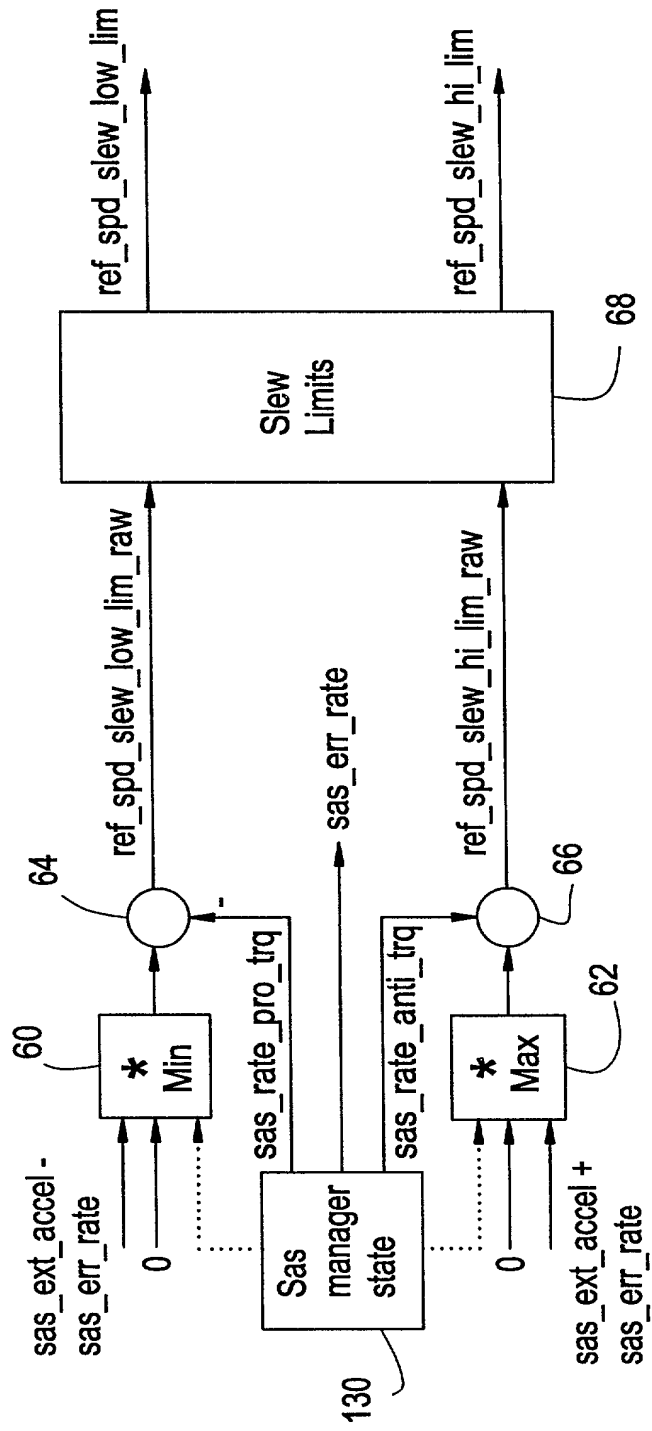
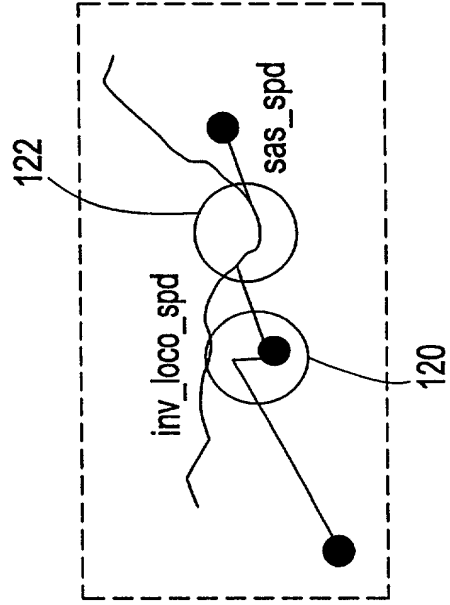


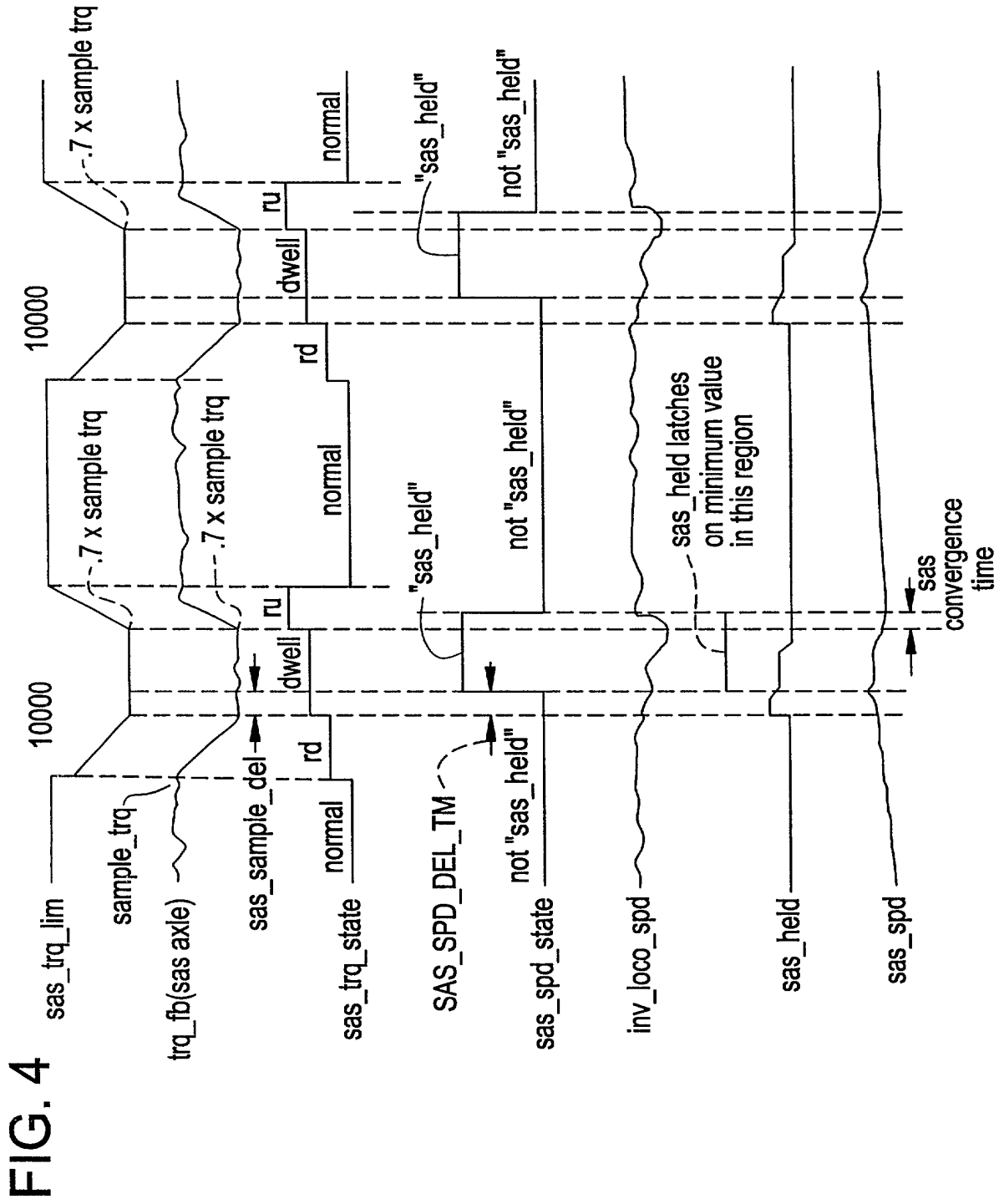
FIG. 2D



\* set output to 0 if not wide or narrow

FIG. 3





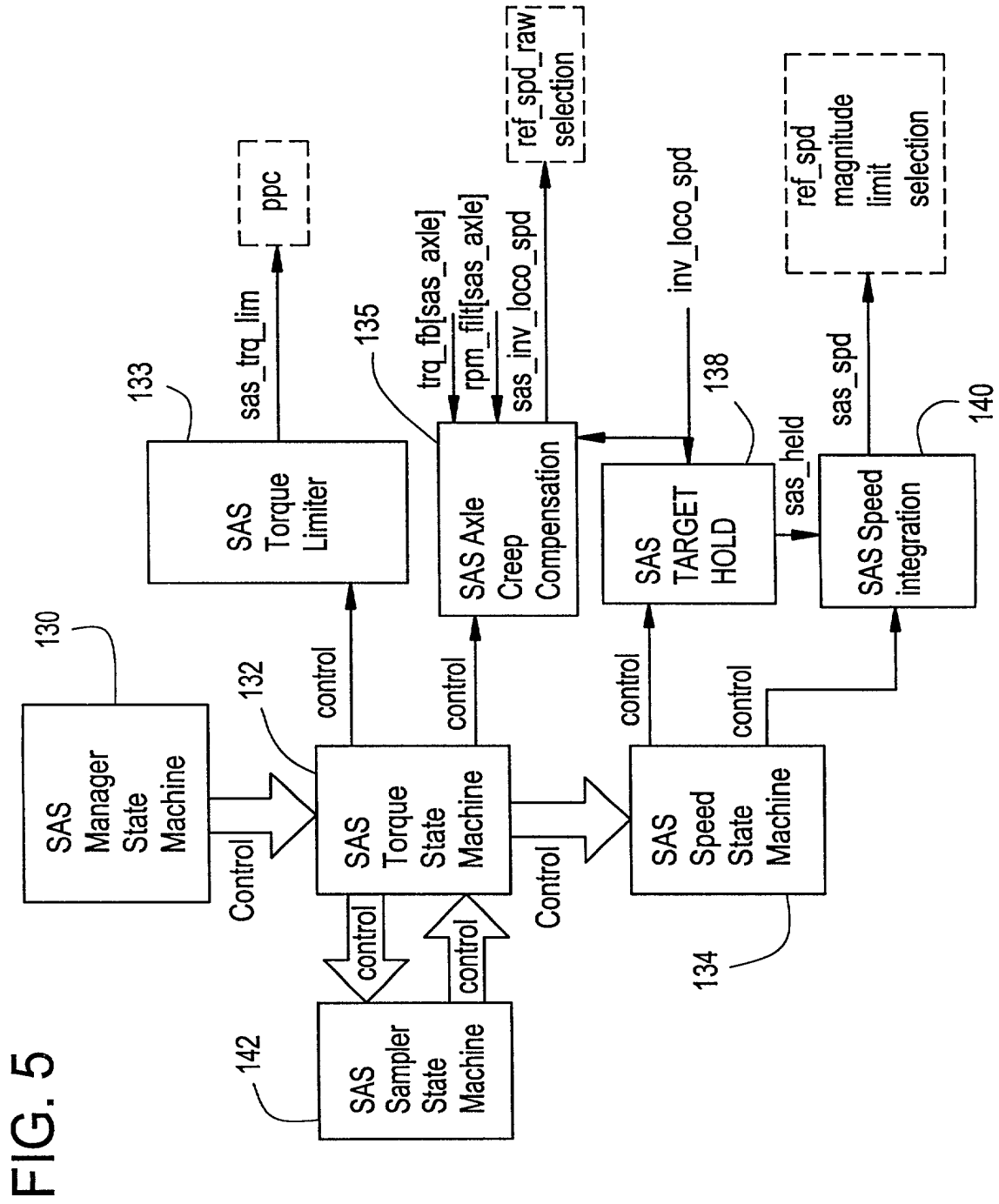




FIG. 6

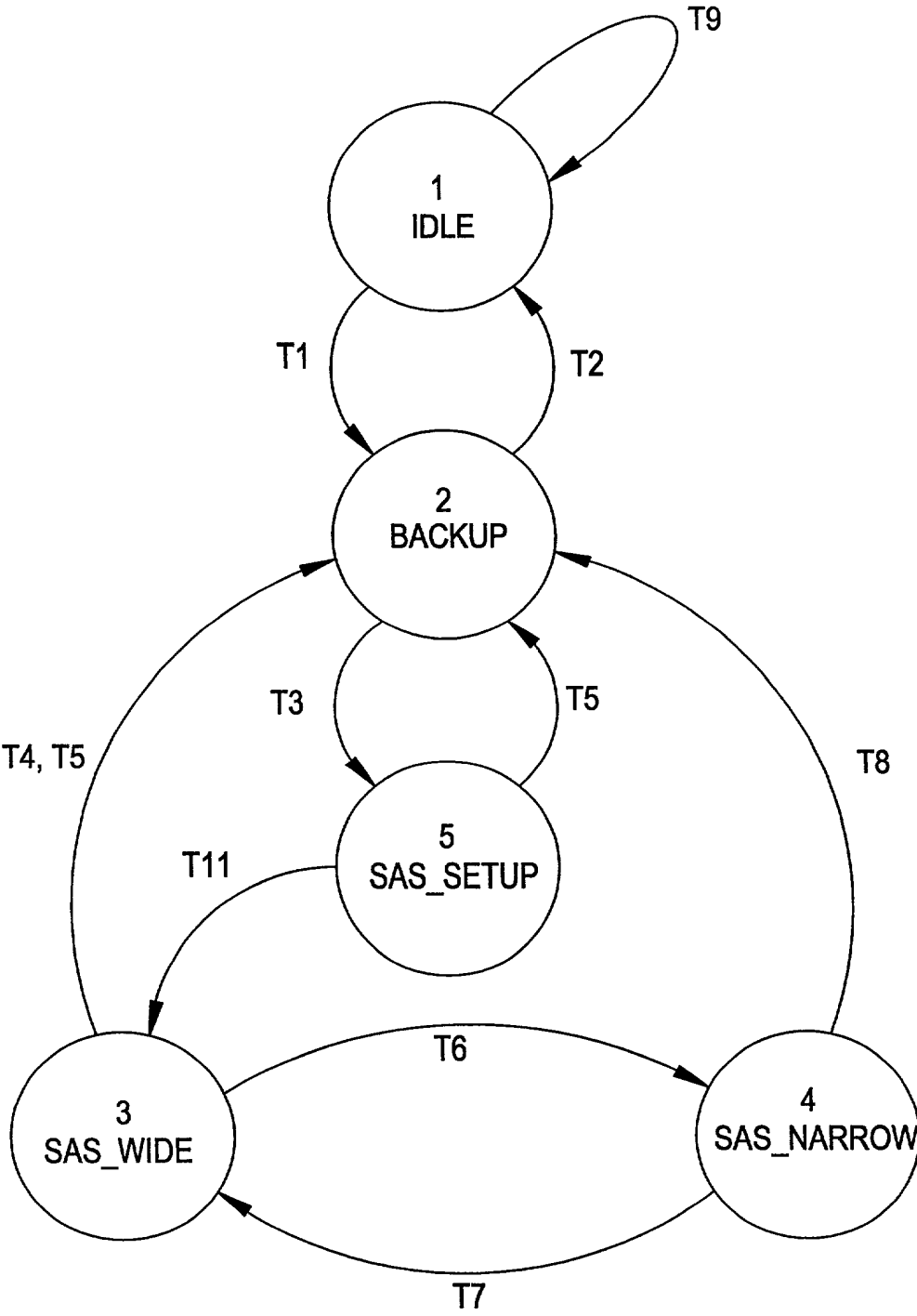


FIG. 7

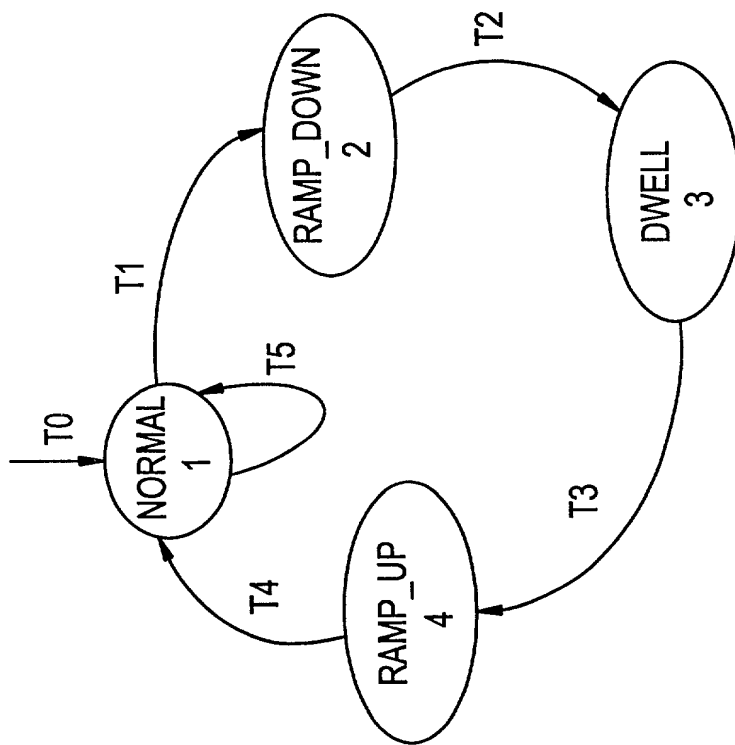
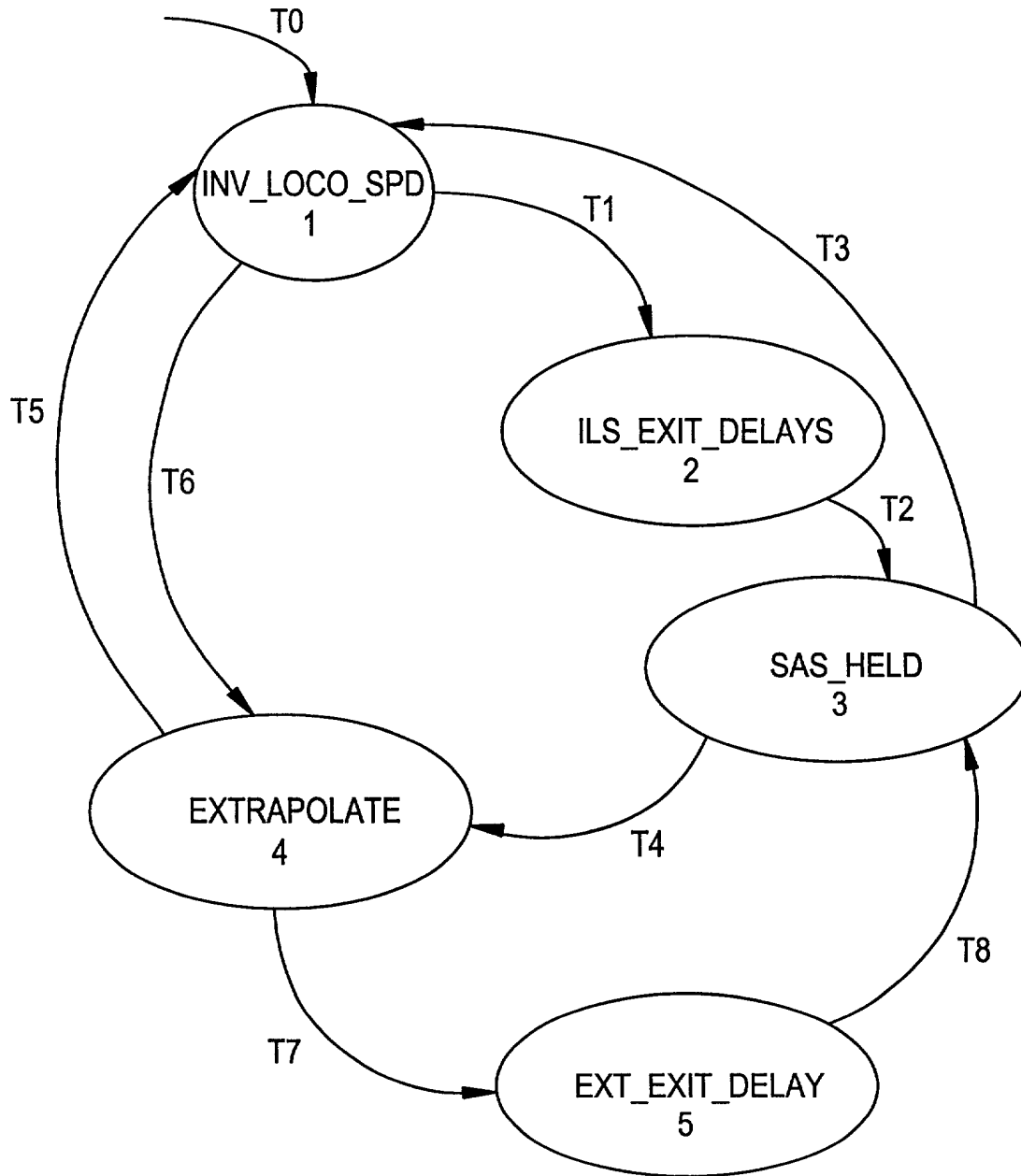


FIG. 8



[illegible]